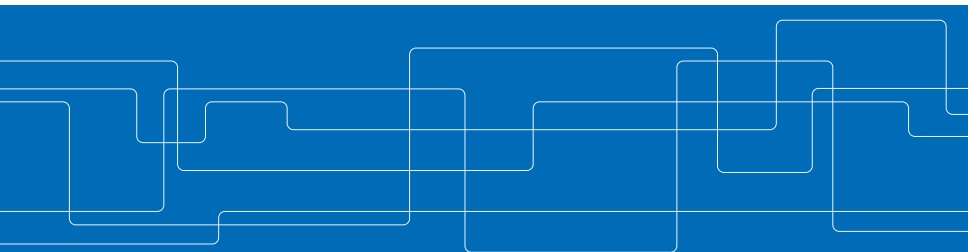


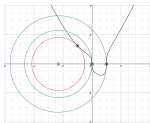
Tangency and Discriminants

FPSAC 2019, Ljubljana

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Goal



- ▶ Discriminants: tangency and duality
- ▶ Discriminants: tangential intersections
- ▶ Generalized Schäfli decomposition

Natural concept

The discriminant is a concept occurring naturally in connection with the way we grasp 3D objects.

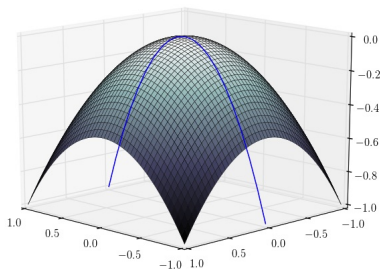


Figure: Boundary locally defined by $f(x, y, z) = 0$. The **Discriminant with respect to x** is the “plane curve” defined by the equation obtained by eliminating x from $\{f = 0, \frac{\partial f}{\partial x} = 0\}$



The discriminants of univariate polynomials

The discriminant: gives information about the nature of the polynomial's roots.

- ▶ the **discriminant** of $c_2x^2 + c_1x + c_0$ is $c_1^2 - 4c_2c_0$.
- ▶ for higher degrees the **discriminant** D_d is a $(2d - 1) \times (2d - 1)$ determinant :

$$D_d = (1/c_d) \det \begin{bmatrix} c_d & c_{d-1} & \cdots & c_0 & 0 & \cdots & 0 \\ 0 & c_d & c_{d-1} & \cdots & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ dc_d & (d-1)c_{d-1} & \cdots & 0 & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 \cdots & \cdots & 2d_2 & c_1 \end{bmatrix}$$



Algebra vs Geometry

Algebra: $D_d = \text{Res}(p(x), p'(x))$

Geometry: $\bullet \xrightarrow{1} \bullet \xrightarrow{x} \bullet \xrightarrow{x^2} \bullet \xrightarrow{x^3} \bullet \xrightarrow{\quad} \bullet \xrightarrow{\quad} \bullet$ $\mathbb{P}^1 \hookrightarrow \mathbb{P}^d$
 $J_1 = \mathcal{O}_{\mathbb{P}^1}(d-1) \oplus \mathcal{O}_{\mathbb{P}^1}(d-1)$ and $\deg(c_1(J_1)) = 2d-2$



The definition of discriminant

Let $\mathcal{A} \subset \mathbb{Z}^n$ be a finite subset of lattice points:

$$\mathcal{A} = \{m_0, m_1, \dots, m_N\}$$

A polynomial p in d variables is **supported on** \mathcal{A} if

$$p(x_1, \dots, x_n) = \sum_{m_i \in \mathcal{A}} c_i x^{m_i}$$

where $x^m = x_1^{k_1} x_2^{k_2} \dots x_n^{k_n}$ if $m = (k_1, \dots, k_n) \in \mathcal{A}$



Figure: Quadrics $c_0 + c_1x + c_2y + c_3xy$



The definition of discriminant

Definition

Let $\mathcal{A} = \{m_0, m_1, \dots, m_N\} \subset \mathbb{Z}^n$. The **discriminant** of \mathcal{A} is (if it exists!) a polynomial $D_{\mathcal{A}}(c_0, \dots, c_N)$ in $N + 1$ variables vanishing whenever the corresponding polynomial $p(x) = \sum_{m_i \in \mathcal{A}} c_i x^{m_i}$ has some multiple root in $(\mathbb{C}^*)^n$.

$$D_{\mathcal{A}}(c_0, \dots, c_N) = 0 \Leftrightarrow \begin{array}{l} \text{there is } x \in (\mathbb{C}^*)^n \text{ s.t.} \\ p(x) = \dots = \frac{\partial p}{\partial x_j}(x) = \dots = 0 \end{array}$$

Otherwise $D_{\mathcal{A}} = 1$.

Existence does not mean an efficient algorithm and hence a formula!



Example 1

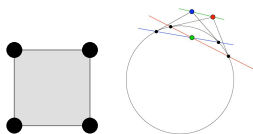
For the configuration $\mathcal{A} = \{(0, 0), (1, 0), (0, 1), (1, 1)\} \subset \mathbb{Z}^2$



The discriminant is given by an homogeneous polynomial $\Delta_{\mathcal{A}}(c_0, c_1, c_2, c_3)$ vanishing whenever the corresponding quadric has a singular point in $(\mathbb{C}^*)^2$. |

$$D_{\mathcal{A}}(c_0, c_1, c_2, c_3) = \det(M) = c_0 c_3 - c_1 c_2.$$

Geometry

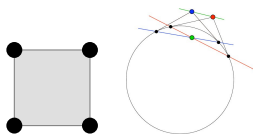


Let $Q \subset \mathbb{C}^2$ and $p \in \mathbb{C}^2$

- ▶ general tangent lines to Q do not contain the point p
- ▶ exceptional locus: $\{x \in Q \mid p \in \mathbb{T}_{Q,x}\}$ has degree 2.
- ▶ It gives the degree of the discriminant.



Geometry

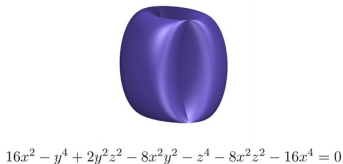
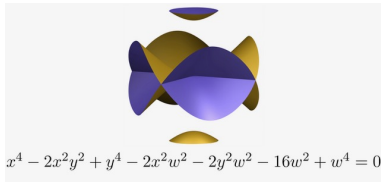


- ▶ The polar classes P_i are codimension i cycles on $X \hookrightarrow \mathbb{P}^N$
- ▶ P_1 on Q is a zero-cycle of degree 2.

Projective duality

$X \hookrightarrow \mathbb{P}^n$ be a smooth embedding of dimension d .
The dual variety is defined as:

$$X^* = \overline{\{H \in (\mathbb{P}^n)^* \text{ tangent to } X \text{ at some } x \in X\}}$$





Projective duality

- ▶ $N(X) = \{(x, H) : H \text{ tangent to } X \text{ at } x \in X\} \subset X \times (\mathbb{P}^N)^*$ has dimension $N - 1$

Bertini For general varieties, the restriction of the projection

$$\pi : N(X) \rightarrow (\mathbb{P}^N)^*$$

is generically 1-1.

- ▶ $Im(\pi) = X^*$, codimension-one irreducible subvariety (generically!)
- ▶ It is defined by an irreducible polynomial D_X , called the discriminant.



Polar geometry: the degree and dimension of the discriminant

Let $P_0(X), \dots, P_n(X)$ be the polar classes.

Theorem

X projective variety of dimension n , then

- ▶ $\text{codim}(X^*) = 1 + n - \max\{j \text{ s.t. } P_j(X) \neq 0\}$
- ▶ Let $\text{codim}(X^*) = 1 + n - j$ then $\text{deg}(X^*) = \text{deg}(P_j(X))$.

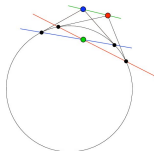


Figure: C^* is another conic, $\text{deg}(P_1(X)) = 2$



Toric projective duality = \mathcal{A} -discriminants

- ▶ $\mathcal{A} = \{m_0, \dots, m_N\} \subset \mathbb{Z}^n$ Let $P_{\mathcal{A}} = \text{Conv}(\mathcal{A})$
- ▶ $\varphi_{\mathcal{A}} : (\mathbb{C}^*)^n \rightarrow \mathbb{P}^N$, $\varphi(x) = (x^{m_0}, \dots, x^{m_N})$
- ▶ $X_{\mathcal{A}} = \overline{\text{Im}(\varphi_{\mathcal{A}})}$ is a toric embedding
- ▶ $X_{\mathcal{A}}^*$ has codimension 1 unless $X_{\mathcal{A}}$ is a linear fibration ($P_{\mathcal{A}}$ certain Cayley polytope).
- ▶ Smooth: codimension 1 if $P_n(X_{\mathcal{A}}) = \deg(D_{\mathcal{A}}) = \sum_{F \preceq P_{\mathcal{A}}} (-1)^{\text{codim}(F)} (\dim(F) + 1)! \text{Vol}_{\mathbb{Z}}(F) \neq 0$



$$(x, y) \rightarrow (1, x, y, xy)$$

$$3! \cdot \text{Area} - 2!(\text{perimeter}) + 4 =$$

$$6 - 8 + 4 = 2$$



Can a discriminant govern multiple roots of systems of polynomials?

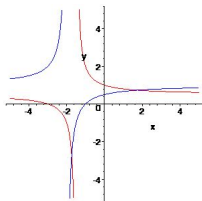
As before: Let $\mathcal{A}_1, \dots, \mathcal{A}_n$ be (finite) in \mathbb{Z}^n and let f_1, \dots, f_n be Laurent polynomials with these support sets and coefficients in an alg. cl. field K , e.g. \mathbb{C} :

$$p_{\mathcal{A}_i}(x) = \sum_{a \in \mathcal{A}_i} c_{i,a} x^a.$$

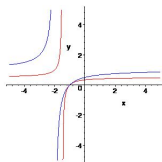
If the coefficients $c_{i,a}$ are generic then, by *Bernstein's Theorem*, the number of common solutions in the algebraic torus $(\mathbb{C}^*)^n$ equals the *mixed volume* $MV(Q_1, Q_2, \dots, Q_n)$ of the Newton polytopes $Q_i = \text{conv}(\mathcal{A}_i)$ in \mathbb{R}^n .

Example

Let $n = 2$ and $\mathcal{A}_1 = \mathcal{A}_2 = \{(0, 0), (1, 0), (0, 1), (1, 1)\}$ be the unit square,
 $f_1 = a_{00} + a_{10}x_1 + a_{01}x_2 + a_{11}x_1x_2$, $f_2 = b_{00} + b_{10}x_1 + b_{01}x_2 + b_{11}x_1x_2$.



— $\frac{1-x_2y_2x_1y_1}{3x_1-3y_2-2x_1y_1}$

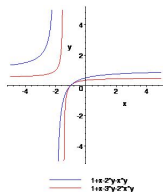


— $\frac{1-x_2y_2x_1y_1}{1-x_1y_2-2x_1y_1}$



tangential intersections

tangential intersections



Given p_{A_1}, p_{A_2} , we say that x is a tangential solution of the system $p_{A_1}(u) = p_{A_2}(u) = 0$ if x is a regular point of the hypersurfaces $p_{A_i} = 0$ and their normal lines are dependent.

Definition

Given a system of type (A_0, \dots, A_r) . We call an isolated solution $u \in (\mathbb{C}^*)^n$ a *non-degenerate multiple root* if the $r + 1$ gradient vectors $\nabla_x p_{A_i}(u), i = 0, \dots, r$ are linearly dependent.



The mixed discriminant

Given $\mathcal{A}_0, \dots, \mathcal{A}_r \subset \mathbb{Z}^n$

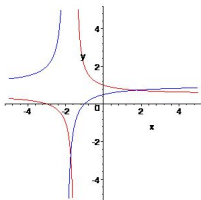
Definition

The **mixed discriminant** is a (the!) polynomial $MD_{\mathcal{A}_0, \dots, \mathcal{A}_r}(c)$ on the $c_{i,a}$ which vanishes whenever the polynomials have tangential roots.

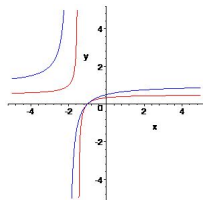
$MD_{\mathcal{A}_0, \dots, \mathcal{A}_r}(c)$ is a polynomial in $|\mathcal{A}_0| + \dots + |\mathcal{A}_r|$ variables
When $\mathcal{A}_0 = \dots = \mathcal{A}_r = \mathcal{A}$ we denote it by $M(r, \mathcal{A})$.

Example

Let $n = 2$ and $\mathcal{A}_1 = \mathcal{A}_2 = \{(0, 0), (1, 0), (0, 1), (1, 1)\}$ be the unit square,
 $f_1 = a_{00} + a_{10}x_1 + a_{01}x_2 + a_{11}x_1x_2$, $f_2 = b_{00} + b_{10}x_1 + b_{01}x_2 + b_{11}x_1x_2$.



— $1 \times 2 \times y \times y$
 — $3 \times 3 \times y \times x \times y$



— $1 \times 2 \times y \times y$
 — $1 \times 3 \times y \times x \times y$

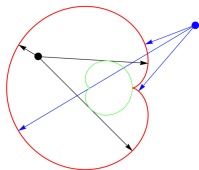
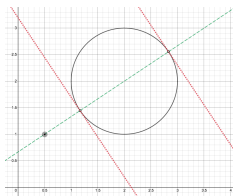
$\Delta_{\mathcal{A}_1, \mathcal{A}_2}$ is the **hyperdeterminant** of format $2 \times 2 \times 2$:

$$a_{00}^2 b_{11}^2 - 2a_{00}a_{01}b_{10}b_{11} - 2a_{00}a_{10}b_{01}b_{11} - 2a_{00}a_{11}b_{00}b_{11} + 4a_{00}a_{11}b_{01}b_{10} + a_{01}^2 b_{10}^2 + 4a_{01}a_{10}b_{00}b_{11} - 2a_{01}a_{10}b_{01}b_{10} - 2a_{01}a_{11}b_{00}b_{10} + a_{10}^2 b_{01}^2 - 2a_{10}a_{11}b_{00}b_{01} + a_{11}^2 b_{00}^2$$

bidegree = (2, 2)

One more example: The distance to a variety

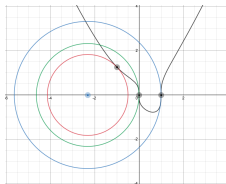
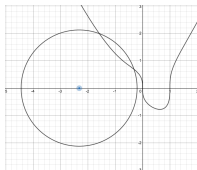
Consider $X \subset \mathbb{R}^N$. The **Euclidian Distance Degree**, $EDD(X)$,



number of critical points of the algebraic function:

$u \mapsto d_u^2(X)$ where $d_X(u) = \min_{x \in X} (d_u(x))$ for $u \in \mathbb{R}^N$ generic.

Consider now a plane curve. Equivalently one looks at the circles admitting tangent solutions with the curve.



C is a conic: 3×3 matrix $M(c_{ij})$ and the circle by the the 3×3 symmetric matrix $M(u, r)$.

The *Mixed Discriminant* is given by the $2 \times 3 \times 3$ hyperdeterminant: $H(c_{ij}, u, r)$.



This proves:

Theorem (Cayley)

Let C be an irreducible conic, then

- ▶ $EDD(\text{Circle}) = 2$
- ▶ $EDD(\text{Parabola}) = 3$
- ▶ $EDD = 4$ otherwise

The key tool is the use of *Schläfli decomposition*

$$MD(A_1, A_2) = \text{Hyperdet}([M_1, M_2]) = \text{Disc}_t(\det(M_1 + tM_2)).$$



Singular intersection of Quadric Surfaces

- ▶ Brownic[1906],
- ▶ Salmon [1911]
- ▶ Farouki [1989]

Completely classified singular intersections of quadric surfaces.

Key tools:

- ▶ Classified by the Hyperdeterminant, i.e. **discriminant of Segre embeddings**
- ▶ The hyperdeterminant can be computed by **iteration**



Two Main Questions:

- ▶ **Question 1** Can the mixed discriminant be computed via iteration?
- ▶ **Question 2** What about singular intersection of higher dimensional quadrics?



Towards an answer to question 1

Theorem (Dickenstein-DR-Morrison 2019)

$$MD_{r,A} = D_{\text{Cayley}(r,A)}$$

Definition

Let $\mathcal{A} \subset \mathbb{Z}^d$, such that $D_{\mathcal{A}} \neq 1$, $\deg(D_{\mathcal{A}}) = \delta$, and let $(\lambda_0, \dots, \lambda_r) \in \mathbb{C}^{r+1}$. Define the **iterated discriminant** as:

$$ID_{r,\mathcal{A}} = D_{\delta\Delta_r}(D_{\mathcal{A}}(\lambda_0 f_0 + \dots + \lambda_r f_r))$$

Abuse of notation: $f_i = (c_0^i, \dots, c_N^i)$
 $\deg(I_{r,\mathcal{A}}) = \delta(\delta - 1)(r + 1)$



Answer to question 1

Theorem (Dickenstein-DR-Morrison)

$\mathcal{A} \subset \mathbb{Z}^n$, $D_{\mathcal{A}} \neq 1$ and $0 \leq r \leq n$. Then, the mixed discriminant $MD_{r,\mathcal{A}} \neq 1$ divides the iterated discriminant $ID_{r,\mathcal{A}}$. Moreover,

1. If $\text{codim}_{X_{\mathcal{A}}^*}(\text{sing}(X_{\mathcal{A}}^*)) > r$, $ID_{r,\mathcal{A}} = MD_{r,\mathcal{A}}$.
2. If $\text{codim}_{X_{\mathcal{A}}^*}(\text{sing}(X_{\mathcal{A}}^*)) = r$, $ID_{r,\mathcal{A}} = MD_{r,\mathcal{A}} \prod_{i=1}^{\ell} Ch_{Y_i}^{\mu_i}$, where Y_1, \dots, Y_{ℓ} are the irreducible components of $\text{sing}(X_{\mathcal{A}}^*)$ of maximal dimension r , with respective multiplicities μ_i .
3. If $\text{codim}_{X_{\mathcal{A}}^*}(\text{sing}(X_{\mathcal{A}}^*)) < r$, $ID_{r,\mathcal{A}} = 0$.



Answer to question 2

Theorem (Dickenstein-DR-Morrison)

Let Q_1, Q_2 be two d -dimensional quadric hypersurfaces then:

$$Q_1 \cap Q_2 \text{ singular if and only if } I_{1,2\Delta_d} = MD_{1,2\Delta_d} = 0$$



(THANK YOU)ⁿ

$n \gg 1$